

LEARNING OBJECTIVES / GOALS / OUTCOMES / LEARNING OUTCOMES:

The student will:

- gain a thorough grasp of Newtonian mechanics, using the technique of free body diagrams
- develop a feel for the order of magnitude of mechanical qualities in realistic situations
- improve his or her problem-solving skills by doing a large number of problems
- gain a taste for the emphasis on computation required for engineering analysis
- learn the standard format for engineering solutions
- be able to solve various problems in each of the topic areas listed in the Calendar Description section

METHODS:

The course will be presented using lectures and tutorials. Approximately ten problems per week will be handed in and marked. During the tutorial the marked assignments will be discussed, additional problems in the same general area will be dealt with, and help will be given for those needing it for the next assignment set. There will be a close coordination between the lecture topics and the tutorials.

PRIOR LEARNING ASSESSMENT RECOGNITION (PLAR):

Credit can be awarded for this course through PLAR (Please check :) Yes No

METHODS OF OBTAINING PLAR:

Please see the Physics PLAR policy on the department's webpage

TEXTBOOKS, REFERENCES, MATERIALS:

[Textbook selection varies by instructor. An example of texts for this course might be:]

R.C. Hibbeler, Engineering Mechanics (Statics and Dynamics), 9th ed., 2000.

F.P. Beer, E.R. Johnston, Vector Mechanics for Engineers, S.I. Metric Ed., 1981 McGraw-Hill

SUPPLIES / MATERIALS:

Engineering Grade Paper and simple drawing instruments

STUDENT EVALUATION:

[An example of student evaluation for this course might be:]

Assignments	15%
Midterm	30%
Final exam	55%

COURSE CONTENT:

[Course content varies by instructor. An example of course content might be:]

<u>WEEK</u>	<u>TOPIC</u>	<u>TEXT</u>
1	Introduction to mechanics, fundamental concepts and principles, systems of units, solution methods and numerical accuracy. Vectors.	Ch 1, 1.1 – 1.6 Ch 2.1 – 2.3
2-2.5	Newton's laws, forces as vectors, free body diagrams and Equilibrium of	Ch 3, 3.1 – 3.4 Ch 4, 4.1 – 4.5
2.5-3	Rigid body equilibrium, torques as vector cross products, equivalent forces and couples. Loadings and distributed forces	Ch 4, 4.4 – 4.10
4	Rigid body equilibrium in two and three dimensions	Ch 5, 5.1 – 5.7
5	Analysis of structures (trusses and frames)	Ch 6, 6.1 -6.4
6	Friction-wedges, square threaded screws, journal bearings, thrust bearings, rolling resistance, belt friction.	Ch 8, 8.1 – 8.3
7	Virtual Work, Conservative Forces and Potentials	
8 – 9	Particle kinematics – rectilinear and curvilinear motion (radial and tangential components)	Ch 11, 11.1 – 11.7
10	Newton's second law, linear and angular momentum, Central force problems	Ch 12, 12.1 – 12.9

11	Energy and Momentum conservation – work-kinetic energy theorem, momentum-impulse theorem, conservative forces	Ch 13, 13.1 – 13.7
12	Systems of particles, work and energy, momentum and angular momentum	Ch 14 pp. 655-729 14.1 – 14.6
13	Systems of particles, Momentum and Impulse, Angular Momentum and Angular Impulse	Ch 15, 15.1 – 15.7